

# Accurate and Scalable RTL-level Fault Injection Simulation for Industrial and Automotive Standards

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### **Overview and Executive Summary**

### • **Problem**

- **Industrial and automotive standards (ISO 26262) require that the fault coverage be reported at the gate-level.**
- **Fault injection-based techniques are not scalable to industrial Systems on a chip (SoC).**
- **Existing fault-injection-free RTL-level fault simulators do not meet the required fault coverage standards.**

### • **Project Description**

- **Fault-injection-free simulation for the test sequence.**
- **An abstract quantity (metric) at each RTL module estimates accurately the fault coverage at the module.**
- **Probabilistic inter-module error propagation.**
- **Statistical evaluation framework to ensure accuracy of the estimated fault coverage so that it meets the ISO standards.**

## **Approach**

#### • **Novelty**

- **Intra-module fault coverage using metrics.**
- **Inter-module error propagation.**
- **Statistical evaluation framework.**
- **Scalable Intra-Module Coverage using metrics**
	- **Probabilistic Metric:**
		- **0/1 line controllabilities with a logic simulation for sequence.**
		- **Calculate fault observabilities using controllability values [1].**
		- **Fault detectability: Product of controllability and observability.**
	- **Critical Path Trace metric [2]:**
		- **Pessimistic fault coverage that uses a single logic simulation and one back-trace per output cone.**
	- **Metrics will be evaluated.**

[1] L.T. Wang, Y.W. Chang , K.T. Cheng, "Electronic Design Automation", Morgan Kaufmann, February 2009

[2] M. Abramovici, P. R. Menon and D. T. Miller, "Critical Path Tracing - An Alternative to Fault Simulation," Proc. 20th Design Automation Conference, pp. 214-220, June 1983.

## **Approach**

- **Probabilistic Inter-Module Error Propagation**
	- **Boolean difference function based on SoC functionality**
	- **Disjoint covers determine error propagation probability**



- **O(t)=f(l<sub>6</sub>(t-1))=f(j(l<sub>4</sub>(t-2),l<sub>5</sub>(t-2))= f(j(k(l<sub>1</sub>(t-3),l<sub>2</sub>(t-3),l<sub>3</sub>(t-3)), l<sub>5</sub>(t-2))**
- **Fault is at I<sup>5</sup> is observed twice in the functional expansion of the output**
- **Probability is estimated by choosing disjoint covers which satisfy the Boolean difference of the function**

## **Approach**

- **Statistical Framework: Linear regression analysis**
	- **Determine the correlation between fault cover by proposed metric (m\_cover) and actual fault cover (***i* **is the sequence size) [1]:**

• 
$$
r_{m\_cover,fc} = \frac{cov(m\_cover,fc)}{\sigma_{m\_cover}\sigma_{fc}} = \frac{\sum_{i=1}^{n}(m\_cover_i - \overline{m\_cover}) \times (fc_i - \overline{fc})}{\sqrt{\sum_{i=1}^{n}(m\_cover_i - \overline{m\_cover})^2} \times \sqrt{\sum_{i=1}^{n}(fc_i - \overline{fc})^2}}
$$

- **Best fit line for number series** *m\_cover<sup>i</sup> , fc<sup>i</sup>* **is found with regression analysis**
- **Accuracy of the approach is determined by obtaining the residuals (difference between actual and estimated fault cover).**
	- **For each set of data points (m\_cover<sup>i</sup> ,fci ), the mean of residuals must be zero**
	- **For each set of data points (m\_cover<sup>i</sup> ,fci ), the variance of residuals must be a constant value**
	- **The residuals should be uncorrelated with each other**
	- **The residuals should be normally distributed**

[1] EAGLE: A Regression Based Model for Fault Coverage Estimation Using a Simulation Based Metric (ITC-2014)

# **Project Tasks/ Deliverables**



#### • **Potential Member Company Benefits**

- **Fast and accurate grading tool to estimate the quality of a given test set in order to assess whether ISO 26262 standards have been met**
- **Thorough experimental evaluation on industrial benchmarks provided by the sponsor company**